

I Introduction

11.10.22

Plan: Have a "long" introduction in order to

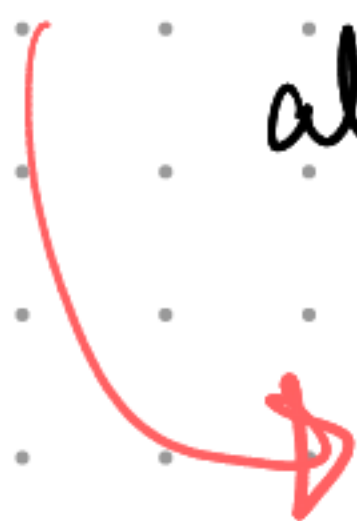
- provide some motivation for the (partly) more "technical" content that will come later

- give those participants who were not in the Algebra 2 class last term a little more time to brush up their commutative

algebra knowledge

- (prime) ideals, quotients
- localization
- spectrum of a ring, Zariski topology

further references on moodle page



- What is algebraic geometry?
- (very) rough survey of this class
- I would like to know:
What are your expectations?

also: what is your background/knowledge so far?

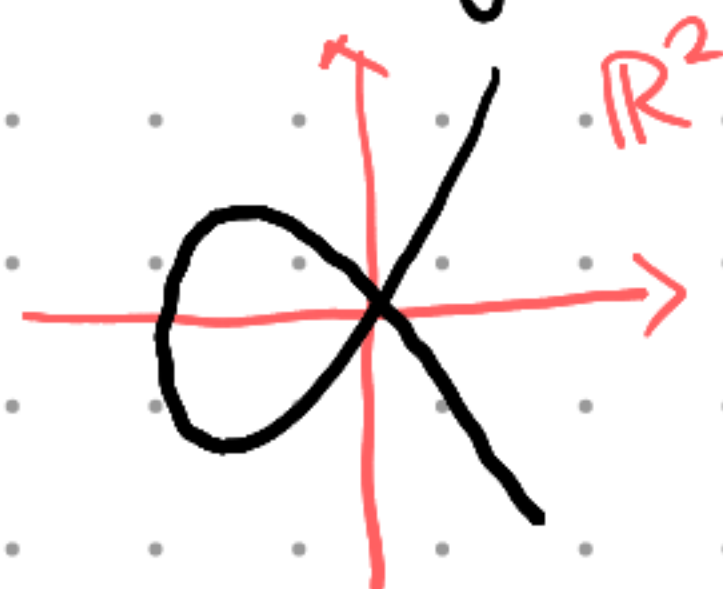
practical/organizational

legendary content

What is algebraic geometry?

→ study "geometric properties" of solution sets of systems of polynomial equations (over a field, or more generally a commutative ring)

Example $\{(x,y) \in \mathbb{R}^2; y^2 = x^2(x+1)\}$



Compared to previous/other courses:

linear algebra	algebra	algebraic geometry	algebraic number th.
systems of linear equations	one polynomial equation, one variable	several pol. equations, several variables	coefficients / solutions in $\mathbb{Z}, \mathbb{Q}, K/\mathbb{Q}$ finite, $\mathbb{F}_q \dots$

What does the "algebraic" in "algebraic geometry" refer to?

→ look at solutions / zero sets of polynomials (rather than, e.g., of (convergent) power series, differentiable / holomorphic functions)

→ use algebraic methods (commutative algebra)

"in principle" can work over arbitrary field

We start with a simple example which illustrates how geometric methods can be useful:

An (algebra-) geometric view on the theorem of Cayley-Hamilton

Theorem \mathbb{k} a field, $A \in M_n(\mathbb{k})$. Then $\text{ch}_A(\text{pol}_X(A)) = 0$
($\in M_n(\mathbb{k})$).

Let us consider the following situation: $\mathbb{k} = \mathbb{R}$,

Want to use that the theorem is obviously true for diagonal matrices, and hence for diagonalizable matrices. In fact, suffices to have diag-able / \mathbb{C} .

trace of A
 $\text{tr}(A) = 0$
not really necessary, but simplifies the notation a little

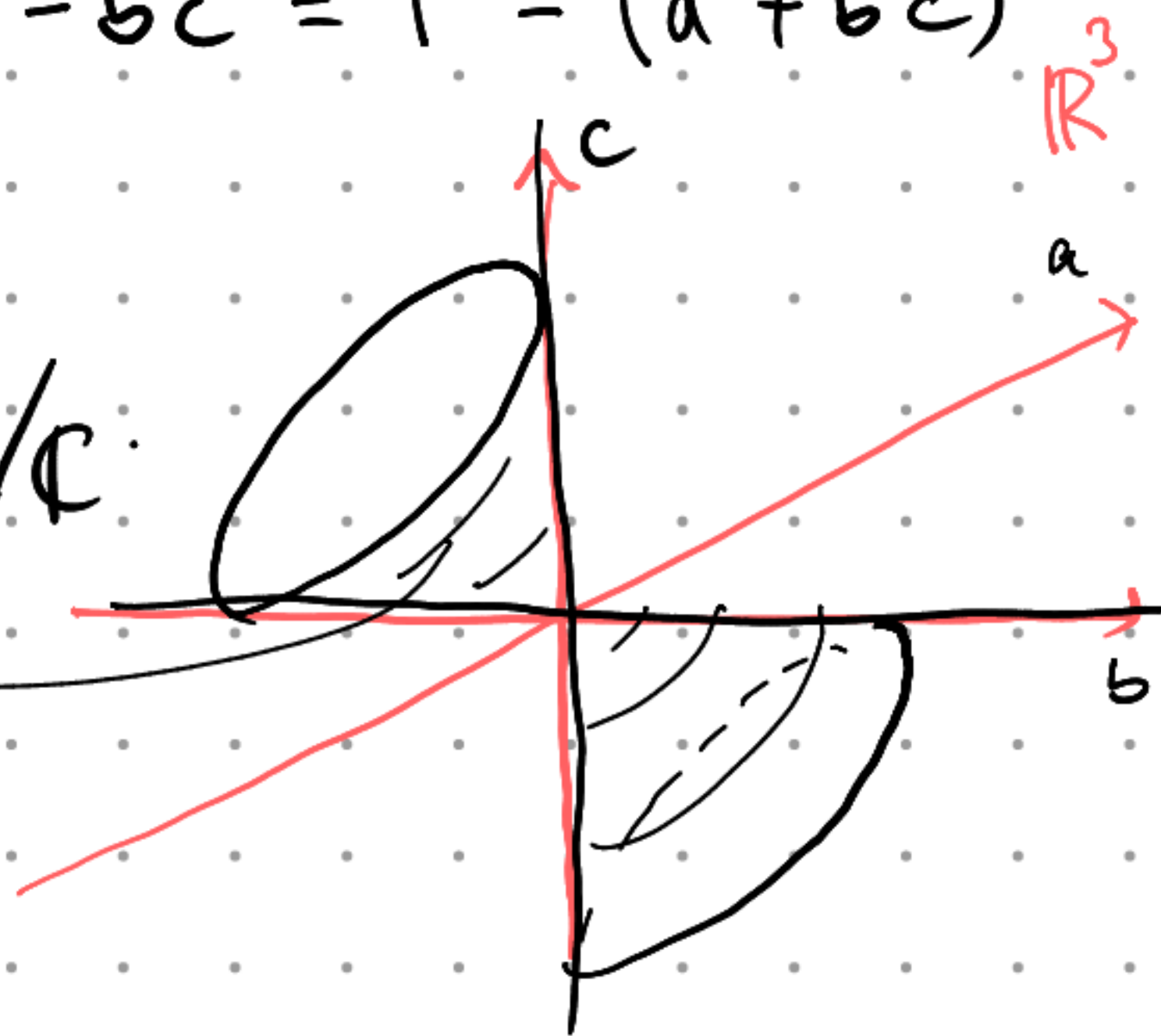
So consider $A = \begin{pmatrix} a & b \\ c & -a \end{pmatrix} \in M_2(\mathbb{R})$ $\text{tr}=0$ $\xrightarrow{\text{as } \mathbb{R}\text{-v.s.}} \mathbb{R}^3$

Have $\text{ch}_A(\text{pol}_X) = (T-a)(T+a) - bc = T^2 - (a^2 + bc)$

\rightarrow all matrices $A = \begin{pmatrix} a & b \\ c & -a \end{pmatrix}$

with $a^2 + bc \neq 0$ are diagonalizable / \mathbb{C} .

cone where $a^2 + bc = 0$



To prove the result for matrices $A = \begin{pmatrix} a & b \\ c & -a \end{pmatrix}$ with $a^2 + bc = 0$,
consider the map

$$M_2(\mathbb{R})^{\text{tr}=0} \xrightarrow{\Sigma} M_2(\mathbb{R}), \quad A \mapsto \text{charpol}_A(A).$$

Goal: $\Sigma(A) = 0$ for all A .

Can view Σ as a map $\mathbb{R}^3 \rightarrow \mathbb{R}^1$ given by
polynomials, hence Σ is continuous.

Since $\{0\} \subset M_2(\mathbb{R})$ is closed, therefore $\Sigma^{-1}(\{0\})$
is closed in $M_2(\mathbb{R})^{\text{tr}=0}$.

We have seen that $M_2(\mathbb{R})^{\text{tr}=0} \setminus V(a^2 + bc) \subseteq \Sigma^{-1}(\{0\})$.

Since $M_2(\mathbb{R})^{\text{tr}=0} \setminus V(a^2 + bc)$ is dense in $M_2(\mathbb{R})^{\text{tr}=0}$,

It follows that $\Sigma^{-1}(\{0\}) = M_2(\mathbb{R})^{\text{tr}=0}$, as desired.

Question: How to deal with other fields?

(See Problem sheets 1, 2.)

The Zariski topology on k^n (k a field)

Since we want to study solution sets of systems of polynomial equations, let us introduce some notation:

k field, $f_1, \dots, f_m \in k[T_1, \dots, T_n]$

$$\leadsto V(f_1, \dots, f_m) = \left\{ (t_i)_i \in k^n ; \forall j=1, \dots, m: f_j(t_1, \dots, t_n) = 0 \right\}$$

Furthermore, if K/k is any field extension, we can also plug elements of K^n into the f_j and define

$$V(f_1, \dots, f_m)(K) = \left\{ (t_i)_i \in K^n ; \forall j: f_j(t_1, \dots, t_n) = 0 \right\}.$$

(V stands for vanishing set (or in German:

Verschwindungsmenge).)

